

# Numerical Simulation of 30P30N Multi-Element Airfoil Using Delayed Detached-Eddy Simulation

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In this paper, an in-house code based on a cell-centered finite difference method using delayed detached-eddy simulation is employed to investigate the aerodynamic and aeroacoustic characteristics of the 30P30N multi-element high-lift airfoil. The experimental data from the Japan Aerospace Exploration Agency and Floride State University are used to make quantitative comparisons with the calculations. Reasonable agreement is achieved in terms of the statistical quantities, the power spectral density of the pressure fluctuations and the velocity fluctuations in the near flowfield. Additional numerical probes have been introduced to investigate the pressure and velocity spectra in the slat cove, main cove, flap suction side and all the wake regions. The slat cove acts as a shallow cavity where narrow-band peak tones accompanying with low-to-moderate broadband frequencies are captured. Besides, the high-frequency tone at 21kHz is caused by the slat trailing-edge vortex shedding and the tone at 40kHz is induced by the main trailing-edge. The spectra around flap component are characteristic by broadband contents due to massive separation on the suction side. Overall, the slat component is considered as a dominant contributor to the noise emission.

# I. Introduction

When the aircraft noise [1][2] related to the propulsion system is reduced remarkably by the advent of quiet high-bypass turbofan engines [3], the airframe noise [4][5][6] becomes a major contributor to the overall noise emissions especially in taking off or landing configurations. Understanding the underling mechanism will be helpful to promote the corresponding noise reduction concepts and will bring great benefit to the civil aviation industry. To progress the capabilities of numerical techniques for airframe noise prediction, a series of international workshops on the benchmark problems for airframe noise computations (BANC) [7] have been held by the American Institute of Aeronautics and Astronautics (AIAA). Since 2010, five subsequent workshops have already been successfully held, which are the BANC-I in Stockholm in 2010, BANC-II in Colorado in 2012, BANC-III in Atlanta in 2014, BANC-IV in Lyon in 2016 and BANC-V in Atlanta in 2018. Over the past decade, extensive efforts have been

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focused on the following canonical problems: (1) the airfoil trailing-edge noise [8]; (2) the landing gear noise [9]; (3) the slat noise of a multi-element high-lift configuration [10].

In terms of the slat noise, two generic configurations are presented in the workshops: the DLR/ONERA three-element airfoil [10][11][12] and NASA's modified 30P30N three-element airfoil [13][14][15]. This paper focus on the latter one: modified-30P30N. Two sets of detailed measurements of the flow and acoustic signals are obtained in the wind tunnel facilities at Japan Aerospace Exploration Agency (JAXA) [16][17] and Florida State University (FSU) [18][19][20][21].

Regarding the computational calculations for 30P30N, majority of the work targets on the mechanism of slat cove. However, less attention is paid on the main and flap components. In the current paper, a detailed numerical investigation on the flow dynamics of the 30P30N configuration is carried out where the instantaneous unsteadiness in flowfield, time-averaged statistics and turbulent structures are focused. Apart from the sensors around slat, additional pressure and velocity sensors are placed surrounding the main and flap components so as to provide more quantitative information.

# II. Methodologies

The compressible Navier-Stokes equations under the curvilinear coordinates are solved:

$$\frac{\partial \hat{U}}{\partial t} + \frac{\partial \hat{E}}{\partial \xi} + \frac{\partial \hat{F}}{\partial \eta} + \frac{\partial \hat{G}}{\partial \zeta} = \frac{Ma}{Re} \left( \frac{\partial \hat{E}_{\nu}}{\partial \xi} + \frac{\partial \hat{F}_{\nu}}{\partial \eta} + \frac{\partial \hat{G}_{\nu}}{\partial \zeta} \right),$$

where the velocity is normalized by sound speed. Two similarity parameters are Mach number (denoted by *Ma*) and Reynolds number (denoted by *Re*).

$$Ma = \frac{u_{\infty}^{*}}{a_{\infty}^{*}}, \quad Re = \frac{\rho_{\infty}^{*}u_{\infty}^{*}L^{*}}{\mu_{\infty}^{*}}, \quad \frac{Ma}{Re} = \left(\frac{\rho_{\infty}^{*}a_{\infty}^{*}L^{*}}{\mu_{\infty}^{*}}\right)^{-1}, \quad \rho = \frac{\rho^{*}}{\rho_{\infty}^{*}}, \quad p = \frac{p^{*}}{\rho_{\infty}^{*}\left(a_{\infty}^{*}\right)^{2}}, \quad T = \frac{T^{*}}{T_{\infty}^{*}}, \quad e = \frac{e^{*}}{\left(a_{\infty}^{*}\right)^{2}},$$

$$(u, v, w, a) = \frac{\left(u^{*}, v^{*}, w^{*}, a^{*}\right)}{a_{\infty}^{*}}, \quad (x, y, z) = \frac{\left(x^{*}, y^{*}, z^{*}\right)}{L^{*}}, \quad t = \frac{t^{*}a_{\infty}^{*}}{L^{*}},$$

Then the incoming flow variables are:

$$\rho_{\infty} = 1, \quad p_{\infty} = \frac{1}{\gamma}, \quad T_{\infty} = 1, \quad e_{\infty} = \frac{1}{\gamma(\gamma - 1)} + \frac{M^{2}}{2}, \quad (u_{\infty}, v_{\infty}, w_{\infty}, a_{\infty}) = (Ma, 0, 0, 1).$$

# A. High order cell-centered finite difference method

Simulating turbulence and aeroacoustics requires high-order high-resolution methods. A detailed description of the cell-centered finite difference method (CCFDM) can be found in Refs. [22][23], where the flow-dependent variables (density, velocity, pressure, temperature etc.) are stored on the cell centers and the geometry-dependent variables (geometric coordinates) are stored on nodes, similar to the finite volume formulation. In reality, the 2nd-order cell-centered finite difference method is exactly equivalent to the 2nd-order cell-centered finite volume method [24]. However, the high-order cell-centered finite difference discretization is totally different from the high-order cell-centered finite volume discretization. The high-order CCFDM is highly efficient due to dimensionally-by-dimensionally interpolation whist the CCFVM requires expensive Gaussian quadrature integration [25]. Additionally, the satisfaction of geometric conservation law under the curvilinear coordinates is guaranteed through the elaborately designed cell-centered symmetric conservative matrices method [22][23], which targets on the discretization of transformation metrics and Jacobian.

In this paper, 6th-order optimized linear scheme is used to minimize the numerical dissipation. In terms of the time integration method, the efficiently sub-iterative D3ADI [26] is adopted. 20 sub-iterations are found to give a 4 orders residual reduction.

# B. Turbulence methodology

The Delayed Detached Eddy Simulation (DDES) is utilized for turbulence.

The turbulent viscosity is estimated from the Spalart-Allmaras turbulence model [27], which is given by

$$\mu_t = f_{v1} \rho \tilde{v}$$

$$\frac{\partial \tilde{v}}{\partial t} + u_j \frac{\partial \tilde{v}}{\partial x_j} = \frac{1 + c_{b2}}{\sigma} \left[ \frac{\partial}{\partial x_j} \left( (v + \tilde{v}) \frac{\partial \tilde{v}}{\partial x_j} \right) \right] - \frac{c_{b2}}{\sigma} (v + \tilde{v}) \left( \frac{\partial \tilde{v}}{\partial x_j} \right)^2 + c_{b1} (1 - f_{t2}) \tilde{S} \tilde{v} - \left( c_{wl} f_w - \frac{c_{b1}}{\kappa^2} f_{t2} \right) \left( \frac{\tilde{v}}{d_w} \right)^2,$$

where  $d_w$  is the minimum distance to the wall. The principle of Detached Eddy Simulation (DES) [28] is to replace  $d_w$  with a grid-related scale:

$$d_{DES} = \min(d_w, C_{DES} \Delta_{\max}),$$

where  $\Delta_{\text{max}} = \max(\Delta_x, \Delta_y, \Delta_z)$  and  $C_{DES} = 0.65$ . To remedy the grid-induced separation (GIS) in DES, a new length scale is further given to replace  $d_{DES}$  with the modified  $d_{DDES}$ :

$$\begin{aligned} d_{DDES} &= d_w - f_d \max(0, d_w - C_{DES} \Delta_{\max}), \\ f_d &= 1 - \tanh\left((8r_d)^3\right), \\ r_d &= \frac{v_t + v}{\sqrt{U_{i,t} U_{i,t} \kappa^2 d_w^2}}, \end{aligned}$$

which is called Delayed DES (DDES) [29]. A further modification in this paper to promote the shear-layer instability development comes from Chauvet *et al.* [30]:

$$\Delta_{\omega} = \sqrt{\left(\frac{\omega_{x}}{|\vec{\omega}|}\right)^{2} \Delta y \Delta z + \left(\frac{\omega_{y}}{|\vec{\omega}|}\right)^{2} \Delta z \Delta x + \left(\frac{\omega_{z}}{|\vec{\omega}|}\right)^{2} \Delta x \Delta y},$$

where  $\omega_x/|\bar{\omega}|$ ,  $\omega_y/|\bar{\omega}|$  and  $\omega_z/|\bar{\omega}|$  represents the vorticity along three directions.

#### III. Benchmark validation

Firstly, a benchmark tandem cylinder [31][32][33][34][35] is given as validation to demonstrate the feasibility of the in-house code and the capability of DDES in resolving unsteady turbulent scales. The diameter of circular cylinder is  $D = 0.05715 \, m$ . The spacing is L/D = 3.7. The spanwise length is 3D. The Mach number is Ma = 0.128 and Reynolds number based on the diameter of cylinder is 1.66e5. Fig. 1 shows the instantaneous isosurface colored by the streamwise velocity. Fig. 2 and Fig. 3 show good quantitative comparison with the experimental data.

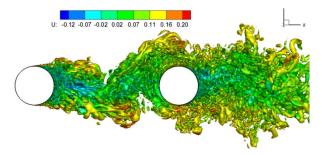


Fig. 1 Isosurface of Q-criterion colored by the streamwise velocity.

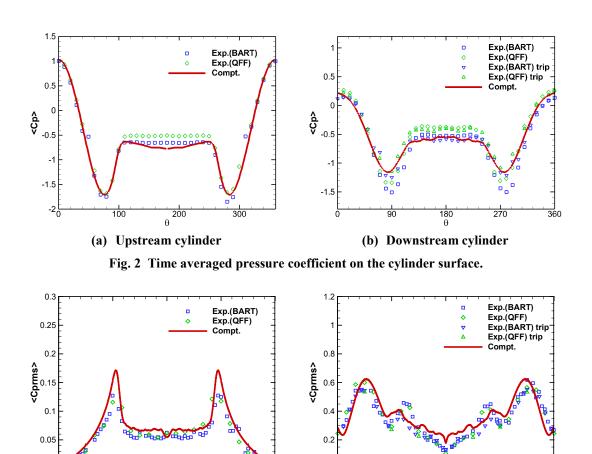


Fig. 3 Root-mean-square pressure coefficient on the cylinder surface.

270

180

(b) Downstream cylinder

## IV. Numerical results of 30P30N

## A. Modified 30P30N airfoil configuration

180 0

(a) Upstream cylinder

270

30P30N configuration, designed by McDonnell-Douglas (now Boeing), consists of three elements, slat, main and flap, where the slat and flap elements are deflected 30 degree relative to the main element chord. The stowed aerodynamic chord is C=0.457m (18 inch), slat chord and flap chord are 0.15C (0.0685m) and 0.3C (0.1371m) respectively. Both slat and flap are deflected 30° to the stowed position. To incorporate the unsteady pressure transducers, the slat trailing-edge is modified to be slightly thicker (0.762mm) than the unmodified one for the BANC workshops. This modification will incur a very high frequency tone.

The incoming Mach number is 0.17 and the Reynolds number based on the stowed aerodynamic chord is 1.7 million. The angle of attack is 5.5 degree. Tab. 1 shows more detailed info about the modified 30P30N configuration. The definition of geometric parameters, slat deflection, gap and overlap relative to the nearest element, are given in the doctoral dissertation by Pascioni [36]. In addition, the related numerical publications on the modified-30P30N are summarized in Tab. 2.

Tab. 1 Parameters for the modified 30P30N

| info                   | parameters     | info                    | parameters         |
|------------------------|----------------|-------------------------|--------------------|
| Stowed chord length    | C = 0.457m     | -                       | -                  |
| Slat deflection angle  | $30^{\circ}$   | Chord of slat           | Cs = 0.15C         |
| Flap deflection angle  | $30^{\circ}$   | Chord of flap           | Cf = 0.3C          |
| Slat gap               | $G_s = 2.95\%$ | Flap gap                | $G_S = 1.27\%$     |
| Slat overhang          | $O_s = -2.5\%$ | Flap overhang           | $O_f = 0.25\%$     |
| Slat leading thickness | 0m             | Slat trailing thickness | 0.001668C(0.762mm) |
| Ма                     | 0.17           | Re                      | 1.7 million        |
| Angle of attack        | 5.5°           | Span-length             | 0.0508m (0.74Cs)   |

Tab. 2 The available numerical studies on modified-30P30N.

| Authors                    | Year | Method                | Grid (Code)             | Cells, ×10 <sup>6</sup> | Span cells       | Time span, $TU_{\infty}/C$ | Time step, $\Delta t U_{\infty}/C$ |
|----------------------------|------|-----------------------|-------------------------|-------------------------|------------------|----------------------------|------------------------------------|
| Lockard & Choudhari [37]   | 2011 | Comp.<br>DDES         | Str.<br>(CFL3D)         | 62                      | 129              | 10.92                      | 2.8×10 <sup>-4</sup>               |
| Locard et al. [38]         | 2014 | Comp.<br>ILES         | Str. (CFL3D & OVERFLOW) | 62<br>73.2              | 129              | 8                          | 2.76×10 <sup>-4</sup>              |
| Terracol et al. [39]       | 2015 | Comp.<br>DDES/ZDES    | Str.                    | 73.6                    | 271              | 10                         | 2.7×10 <sup>-5</sup>               |
| Ashto et al.[40]           | 2016 | Comp.<br>SST-IDDES    | Unstr.<br>(STAR-CCM+)   | 73.6                    | 271              | 7                          | 1.46×10 <sup>-4</sup>              |
| Zhang et al.[41]           | 2017 | Comp.<br>WMLES        | Str.                    | 56.1                    | 85               | 12                         | 1.7×10 <sup>-5</sup>               |
| Gao et al. [42]            | 2017 | Comp.<br>DDES         | Unstr.<br>(SD)          | 0.34                    | 10               | -                          | -                                  |
| Shi <i>et al</i> . [43]    | 2018 | Comp.<br>ILES         | Unstr.<br>(FR/CPR)      | 1.61<br>5.44            | 68               | 19                         | $6.38 \times 10^{-5}$              |
| Ishida [44]                | 2019 | Boltz.<br>LBM         | Str. & Cart.            | 6.7<br>54<br>430        | -                | -                          | -                                  |
| Housman et al. [45]        | 2019 | Comp.<br>ZDES         | Str.<br>(LAVA)          | 36.7                    | 256<br>128<br>64 | 12.76                      | -                                  |
| Sakai <i>et al.</i> [46]   | 2019 | Comp.<br>DDES         | Unstr.                  | 55.7                    | 128              | 11.2                       | $1.87 \times 10^{-5}$              |
| Ueno & Ochi [47]           | 2019 | Comp.<br>SA-DDES      | Unstr.                  | 61<br>242               | -                | 10.4                       | $7.5 \times 10^{-5}$               |
| Kojima <i>et al</i> . [48] | 2020 | Comp.<br>Embedded LES | Unstr.<br>(FaSTAR)      | 80                      | -                | -                          | 1.43×10 <sup>-5</sup>              |
| Present                    | -    | Comp.<br>DDES         | Str.                    | 27                      | 44               | 2.3                        | 2.×10 <sup>-5</sup>                |

# B. Computational setup

The current multiblock structured grid comes from the JAXA website [49]. The computational domain extends 90 chords away from the airfoil. The zoomed 2D cross-section view is shown by Fig. 4. The maximum  $\triangle y+$  far from the wall is estimated to be 1.5. To capture the instability shear layer emitting from the slat leading-edge as well as its impingement onto the lower side of slat, the grid resolution in the slat cove is fine enough, shown by Fig. 4(b). And so does the main cove, main trailing-edge and the suction side of the flap, which is shown by Fig. 4(c). The 3D

grid is generated by extruding the 2D grid in the spanwise direction for a constant length: 0.0508m (corresponding to 0.74Cs), which is the minimum spanwise length determined by the correlation of two-point pressure fluctuations [15]. 44 cells are distributed uniformly along the spanwise direction and the periodic boundary condition is applied. Finally, the 3D grid contains almost 27 million cells in total. In another similar high-lift configuration, the estimated proper spanwise length is Cs [50], a little longer than the present 0.74Cs.

An appropriate choice for time step is also necessary so that a wide range of flow scales can be captured, including the dynamic turbulence structures near the wall, shear layer developments from the slat trailing-edge etc. In this paper, the nondimensionally physical time step is  $\Delta t \, a_\infty/1 = 0.00005$  (corresponding to  $\Delta t \, U_\infty/C = 2.\times 10^{-5}$  and  $\Delta t = 1.5\times 10^{-7} \, s$ ). Our calculation shows that there are about 400 time-intervals per vortex shedding of the slat trailing-edge, which indicates the time resolution is high enough in resolving the fine scales. The DDES simulation continues from a RANS flowfield to reduce the time cost in transient procedure. The transient computation lasts for  $TU_\infty/C = 0.2$ , computation for the statistical quantities is implemented for  $TU_\infty/C = 2.3$ , which is already enough to yield a smooth spectral even though it is shorter than those available in publications. Of course, a longer sampling time will yield a finer identification of the peak tones.

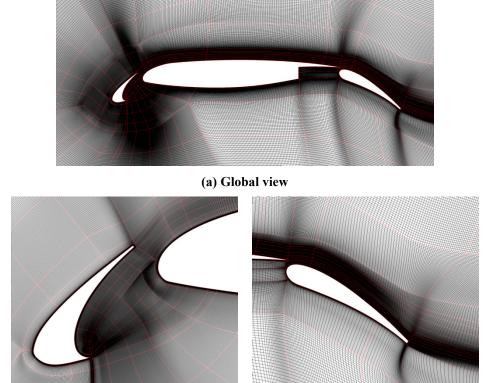


Fig. 4 Computational grid.

(c) Flap

# C. Time averaged pressure coefficients

(b) Slat

The time averaged pressure contour is shown in Fig. 5, where the typical flow structures are marked. The slat and main coves exhibit shallow cavity properties and large recirculation bubbles are formed. The slat leading-edge, slat trailing-edge and main trailing-edge promote the development of shear layers. A flow separation over the backward of flap is clearly observed. And the minimum pressure coefficient exists at the leading suction side of the

main component. This is because, through the gap between slat and main components, the turbulence vortices suffer from strong stretching and accelerating before interacting with the slat vortex shedding wake. Fig. 6 compares the streamlines surrounding the slat cove with the experiment [18].

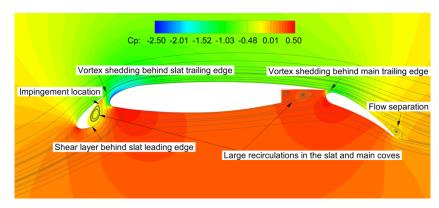


Fig. 5 Pressure coefficient contour.

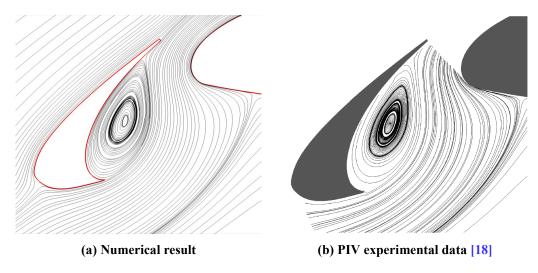


Fig. 6 Averaged streamlines around slat.

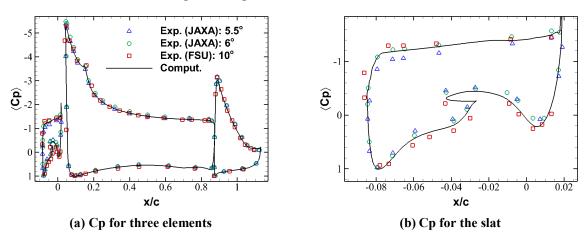


Fig. 7 Averaged pressure coefficients on the surface of 30P30N. The JAXA data in hard wind tunnel for 5.5° and 6° [16], and FSU data in Kevlar wind tunnel for 10° [19].

The time averaged pressure coefficients on the surface of the three elements agree reasonably well with the experimental data in Fig. 7. According to Pascioni and Cattafesta [19],  $\alpha = 10^{\circ}$  from Kevlar wind tunnel in FSU is assumed equivalent to  $\alpha = 5.5^{\circ}$  from hard wind tunnel in JAXA. In addition, the JAXA data with  $\alpha = 6^{\circ}$  is also included in Fig. 7 because it is closest to the calculation result.

#### D. Instantaneous flowfield visulization

The dynamic instantaneous flowfield is shown by the isosurfaces of the scaled Q-criterion colored by local Mach number. Fig. 8 shows the whole 30P30N configuration. Around the slat in Fig. 9, the large recirculation bubble in slat cove, the 2D instability shear layer emitting from the cusp of the leading-edge, the gradually formed 3D vortices structures along the shear layer trajectory and the vortex shedding from the trailing-edge, are all clearly observed. The large recirculation bubble will be demonstrated to associated with the low to moderate narrow-band peak tones, whist the shear layers from the leading cusp and the trailing-edge correspond to high-frequency tones, which will be shown later in the wavenumber domain by Fig. 19. Fig. 10 plots the vortices structures on the upper side of flap where the turbulent boundary layer and the wake flow of main component are convected downstream. A separation region is also visible at the rear of flap.

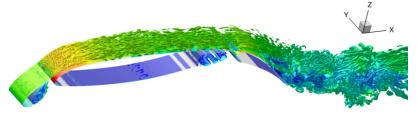


Fig. 8 Isosurface of Q-criterion colored by the Mach number around 30P30N.

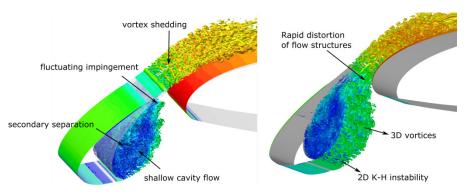


Fig. 9 Isosurface of Q-criterion colored by the Mach number around the slat.

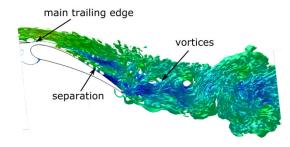


Fig. 10 Isosurface of Q-criterion colored by the Mach number around the flap.

## E. Flowfield contours

The instantaneous spanwise vorticity contour around the slat is compared with the PIV experimental data [18] in Fig. 11. Strong unsteady fluctuations are observed on the shear layer trajectory, which emits from the cusp of the leading-edge firstly, and then they stretch and merge into 3D vortices before finally impinging onto the lower-surface of the slat. Capturing the dynamic flow structures around the impingement region is really challenging because this area not only involves strong interaction of shear layer with the boundary layer but also induces the flow-acoustic feedback loop (narrow-band peaks in Fig. 19 and Fig. 23). Particularly, a portion of the unsteady flows evolves downstream and gets across the gap between slat and main components before finally merging with the slat trailing-edge flows. Another portion of unsteady flow is trapped in the slat cove and interacts with the shear layer at leading cusp to create a recirculation bubble.

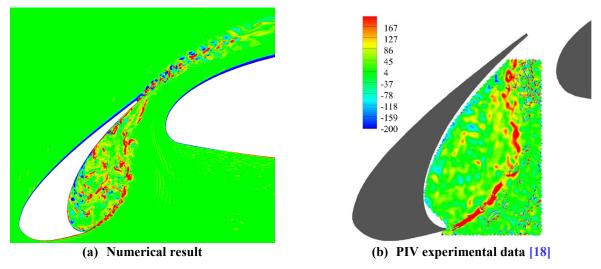


Fig. 11 Instantaneous spanwise vorticity contour around slat. The legend is shown in the figure (b).

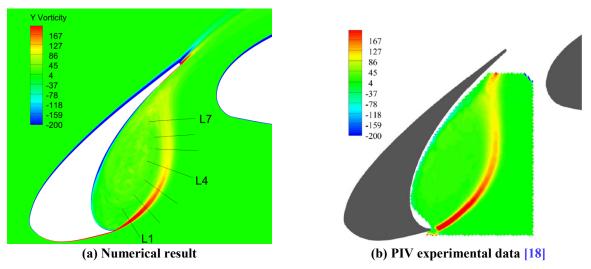


Fig. 12 Time averaged spanwise vorticity contour around slat. The legend is shown in the figure (a).

To quantitatively measure the unsteadiness along the shear layer, the profiles along seven lines are compared. The first comparison is the averaged spanwise vorticity:  $\Omega C/U_{\infty}$ . The contours are given in Fig. 12 where the seven

lines along the shear layer trajectory are depicted in Fig. 12(a). Fig. 13 indicates the calculated results are in good agreement with the measured results. The relative length is normalized by the length of the line itself. "0" represents the left starting point and "1" stands for the right ending point.

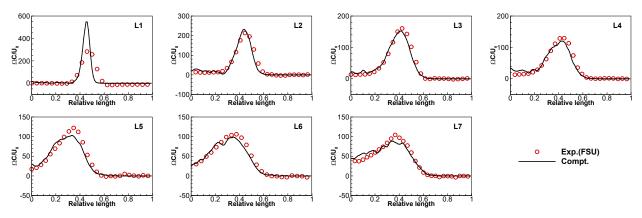


Fig. 13 Spanwise vorticity along the shear layer trajectory at different lines.

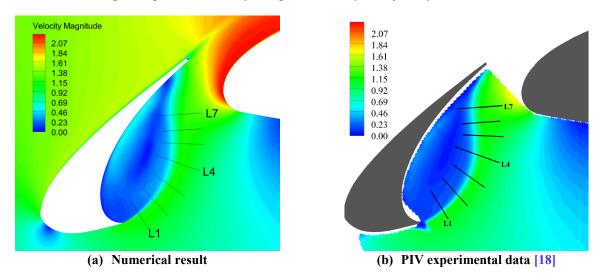


Fig. 14 Time averaged velocity magnitude contour around slat. The legend is shown in the figure (a).

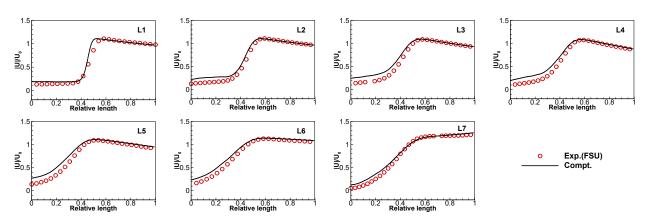


Fig. 15 Velocity magnitude along the shear layer trajectory at different lines.

The velocity magnitude contours ( $|U|/U_{\infty}$ ) are compared in Fig. 14 and the corresponding profiles on seven lines are compared in Fig. 15, where good qualitative and quantitative agreement is obtained.

The turbulence kinetic energy (TKE),  $0.5(\langle uu\rangle + \langle vv\rangle + \langle ww\rangle)/U_{\infty}^2$ , is plotted in Fig. 16 and quantitative comparison along seven cuts with experimental data is shown in Fig. 17. The highest intensities for TKE occur at the reattachment region and the slat trailing-edge region. And a weaker maximum for TKE appears at the slat shear layer, which is due to the laminar-turbulence transition process. TKE can be regarded as a metric for the hydrodynamic intensities and also a useful measurement about the accuracy for aeroacoustic prediction [15]. It is also noted that TKE outside the slat cove is in higher intensity for experiment than calculations. Zhang *et al.* [41] indicates that based on their communications with Pascioni *et al.* [18][19], "the unreasonably high level of TKE in the experimental data is likely caused by poor PIV resolution outside the cove vortex because of a particle shortage in that region". Choudhari and Lockard [15] have also pointed out that the low spatial resolution of PIV processing causes the disparity of the initial shear layer thickness.

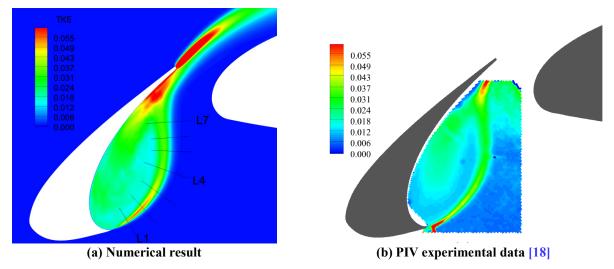


Fig. 16 Time averaged turbulence kinetic energy (TKE) around slat. The legend is shown in the figure (a).

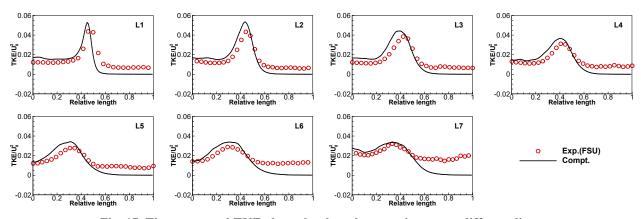


Fig. 17 Time averaged TKE along the shear layer trajectory at different lines.

The studies regarding the flowfield around flap and main is very limited among available literatures. Fig. 18 shows both the instantaneous vorticity field and statistical vorticity field. We can see obviously the unsteady flows due to the trailing-edge vortex shedding from the main component and the flap component. Besides, a massive

separation occurs on the suction side of the flap, which is inevitable for the deflected flap to meet the high lift level [51]. Deck *et al.* adopts a backward step flow to analogy this phenomenon [10].

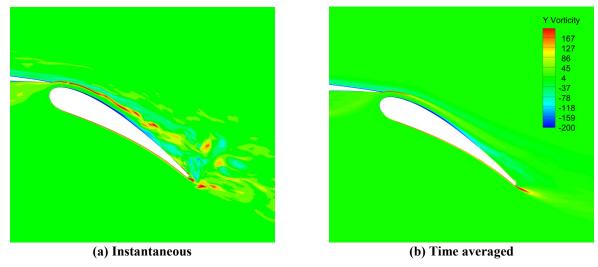
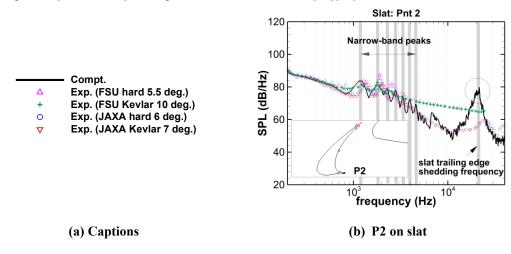


Fig. 18 Spanwise vorticity contour around flap. The legend is shown in the figure (b).

# F. PSD of pressure fluctuations and velocity fluctuations

The power spectral density (PSD) of the dynamic surface pressure fluctuations at five transducers on the slat are shown in Fig. 19 where the experimental data from JAXA [16][17] and FSU [18][19][20] are both used for reference and good agreement is achieved. For P2 and P6, the broadband components are accompanied by several narrow-band peak tones (NBPs) in the low frequency region as well as a very high frequency tone at about 21kHz, which is the signature of vortex shedding from slat trailing edge. The NBPs are probably due to fluid-acoustic feedback loop inside the slat, and the high frequency tone corresponds to the trailing-edge vortex shedding process. Besides, P4 and P5 both exhibit high fluctuation levels because they locate at the impingement region.

Fig. 20 compares the computed PSD with the measured PSD at, M1 and F1, two sensors on the main and flap component, respectively, where only the experiment data from JAXA [16][17] are available.



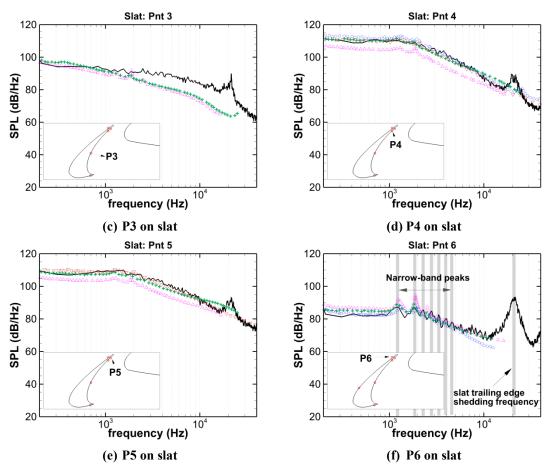


Fig. 19 PSD of surface pressure fluctuations on the slat. Captions are shown in Fig. 19 (a).

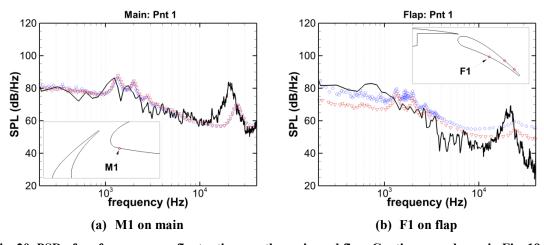


Fig. 20 PSD of surface pressure fluctuations on the main and flap. Captions are shown in Fig. 19 (a).

Furthermore, a snapshot of spanwise pressure gradient superimposed over the spanwise vorticity contours is shown by Fig. 21 where the acoustic radiation is evidently predicted. The slat appears to be a dominant contributor to the noise emission. The flap trailing edge also yields acoustics whose wavelength almost equivalent to that originating from the slat trailing edge. The main trailing edge gives waves with shorter wavelength.

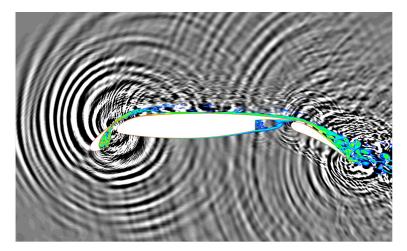


Fig. 21 Snapshot of pressure gradient contour superimposed over the spanwise vorticity contour.

For further analysis, the pressure transducers, SJ1 to SJ6 surrounding the slat is shown by Fig. 22 (a). Fig. 23 compares the PSD of surface pressure fluctuations at SJ1 to SJ6. It is clearly shown that, SJ1, SJ2 and SJ6 exhibit apparent narrow-band peaks at several discrete frequencies: 1243Hz, 1855Hz, 2266Hz, 2792Hz, 3327Hz, 3931Hz and 4531Hz. The interval between two frequencies approximates 600Hz. This is attributed to the resonant feedback mechanism and can be interpreted by the Rossiter modes in cavity (1290Hz and 1935Hz by Terracol *et al.* [39]). Though the present work has not carry out this theoretical part, but more models can be found by Terracol *et al.* [52] and Deck *et al.* [10]. The feedback acoustics are likely caused by the impingement of the shear layer vortices originating from the leading cusp of slat with the upper side of slat. SJ4 and SJ5 are the closest to the impingement location, so strongest turbulence intensities are evidenced.

In addition, the high frequency tone at about 21kHz (25kHz in the experiment) and its first harmonic 42kHz corresponds to the regularly slat trailing-edge vortex shedding. This tone is also predicted numerically by Sakai *et al.* [46] and Ueno *et al.* [47], yet, not one can get the amplitude for this tone exactly agreeing well with experimental data. We also notice a small peak for SJ1 and SJ2 at around 6.5kHz. An approximate peak is also noticed by Terracol *et al.* [39] (7kHz), Lockard *et al.* [38] and Housman *et al.* [45] (6785Hz). Housman claimed this frequency exactly corresponds to the acoustic wavelength equivalent to the spanwise length 0.0508m. Lockard removed this spurious tone by modeling a larger span length.

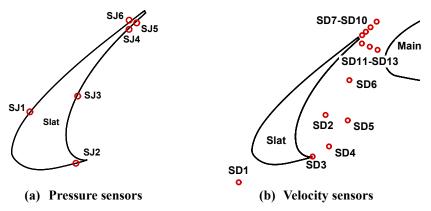


Fig. 22 Sensors surrounding the slat element.

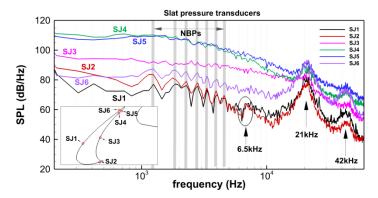


Fig. 23 PSD of surface pressure fluctuations on the slat element.

The fluctuation velocity sensors, SD1 to SD13, are shown by Fig. 22(b). For clarity, we classify these transducers into two categories in terms of their positions. SD1-SD6 are denoted as the first group; SD7-SD13 are denoted as the second group.

Regarding the first group, SD1 lies on the streamline of incoming flow direction, SD2 locates at the center of recirculation bubble and SD3 to SD6 locate on the shear layer trajectory. In Fig. 24, the fluctuation level for SD1 is much lower than that of the other sensors. This is because SD1 locates at the incoming flow streamline where the turbulent level remains small. Besides, SD3 and SD4 yield a visible hump around 21kHz, whereas SD2, SD5 and SD6 yield broadband contents. This hump is linked to the process of the 2D Kelvin-Helmholtz instability development on the shear layer trajectory. By contrast, SD5 and SD6 have been through the transition from 2D laminar to 3D fully-developed turbulence so that the peak is disappeared and a broadband characteristic is predicted. Additionally, SD2, at the recirculation center of the slat cove also exhibits broadband property, but the dynamic intensity level is lower than that of SD5 and SD6.

Regarding the second group (Fig. 25), because SD7 to SD10 are in the near wake of the slat trailing-edge, the three tones at 21kHz, 42kHz and 63kHz, corresponding to the fundamental vortex shedding frequency and the first two harmonics, are apparently observed. SD11 and SD12 behave broadband contents in lower levels.

The acoustic field relating to the slat is shown by Fig. 26.

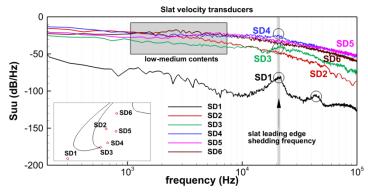


Fig. 24 PSD of streamwise velocity fluctuations around the slat cove region.

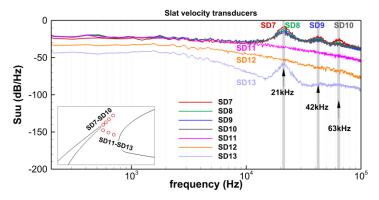


Fig. 25 PSD of streamwise velocity fluctuations around the slat trailing-edge.

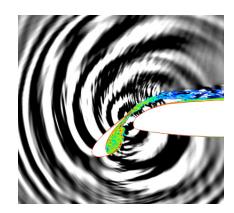


Fig. 26 Pressure gradient contour around the slat element.

The pressure transducers and velocity transducers on the main element are shown in Fig. 27(a) and (b) respectively.

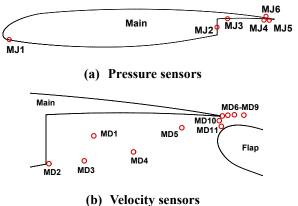


Fig. 27 Sensors surrounding the main element.

Fig. 28 draws the PSD of surface pressure fluctuations at sensors on main component shown by Fig. 27(a). Compared with the sensors on slat in Fig. 23, the turbulent levels for sensors on main component are lower in terms of low to medium frequency (larger than 1kHz and lower than 10kHz). In the high frequency range, MJ1 yields a peak at 21kHz as well as its first harmonic, which owes to the slat trailing-edge vortex shedding. The downstream MJ2 and MJ3 are also affected by the tone at 20kHz. Apart from 20kHz, MJ4, MJ5 and MJ6 also show additional tone at 40kHz, corresponding to the main trailing-edge vortex shedding. This fact indicates MJ4, MJ5 and MJ6 are

affected by all the slat/main/flap trailing edge shedding frequencies. Additionally, the reason for a frequency jump at 6.5kHz has already been explained in the interpretation of Fig. 23.

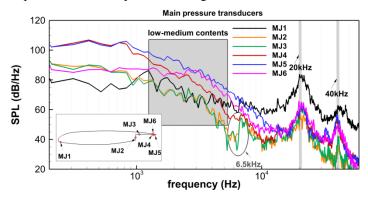


Fig. 28 PSD of surface pressure fluctuations on the main element.

For clarity, we also classify the velocity sensors on main element, MD1 to MD11 shown by Fig. 27 (b), into two categories in terms of their positions. MD1-MD5 are denoted as the first group; MD6-MD11 are denoted as the second group.

Analysis of the first group, MD1 to MD5, is given in Fig. 29. MD1 is at the centroid of the recirculation bubble of the main cove, MD2 to MD5 are on the shear layer emitting from the main cove leading cusp. In terms of the low to medium contents, the fluctuation levels for MD1 and MD2 are evidenced lower than that of MD3 and MD4. Besides, MD5 yields the highest intensity. With regard to high frequency content, a broadband peak at 20kHz is found for MD1 to MD4, which is due to the combination influence of the upstream slat trailing-edge noise and downstream flap trailing-edge noise. MD5 exhibits differently where a peak at 40kHz as well as its harmonic peak at 80kHz is observed. This is easy to be understood because MD5 lies very close to the rear of the main element, so it is obviously affected by the main trailing-edge.

Analysis of the second group, MD6 to MD11, is given in Fig. 30. Since MD6 and MD7 are in the near wake of the main trailing-edge, the tone at 40kHz induced by shedding wake of main component and its several harmonics (around 80kHz, 120kHz, 160kHz, 200kHz *etc.*) are clearly observed. Comparatively, MD8 and MD9, due to their locating further downstream, the peaks disappear and are replaced by broadband parts. Moreover, the evidence that MD10 and MD11 again exhibit the peak tones indicates the gap region between main and flap is largely affected by the main trailing-edge.

The acoustic field relating to the main component is shown by Fig. 31.

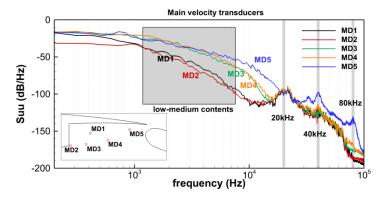


Fig. 29 PSD of streamwise velocity fluctuations around the main cove region.

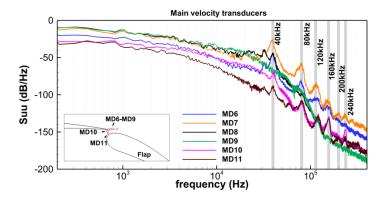


Fig. 30 PSD of streamwise velocity fluctuations around the main trailing-edge.

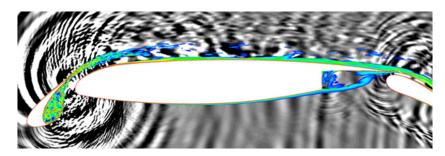


Fig. 31 Pressure gradient contour around the main element.

The pressure transducers (FJ1, FJ2 and FJ3) and velocity transducers (FD1 to FD6) surrounding the flap component are shown in Fig. 32 (a) and (b) respectively.

Fig. 33 draws the PSD of surface pressure fluctuations for sensors FJ1, FJ2 and FJ3. The sensor FJ1 exhibits lower unsteady fluctuation levels than FJ2 and FJ3 in terms of the low and medium range. The broadband hump approximating 8kHz is characterized by the turbulence wake of flap. And the peak tones at 20kHz and 40kHz are induced by the flap trailing-edge vortex shedding.

Fig. 34 demonstrates that all the velocity sensors exhibit a broadband characteristic. And FD1 has lower intensity than the others. Deck *et al.* [10] pointed out the flap flow is analogy to the backward facing step flow.

The acoustic field relating to the flap component is shown by Fig. 35.

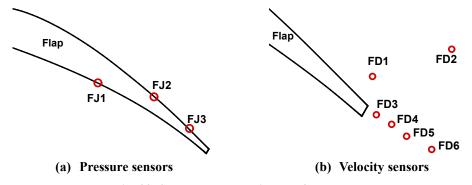


Fig. 32 Sensors surrounding the flap element.

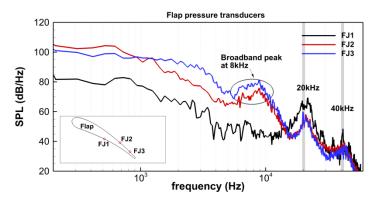


Fig. 33 PSD of surface pressure fluctuations on the flap element.

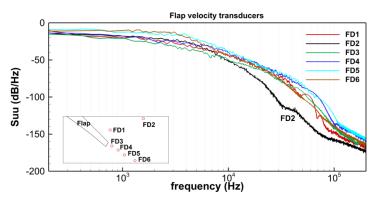


Fig. 34 PSD of streamwise velocity fluctuations around the flap trailing-edge.

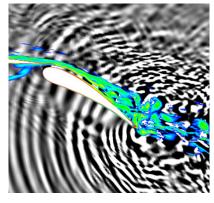


Fig. 35 Pressure gradient contour around the flap element.

# V. Conclusion

In this paper, an in-house code based on a cell-centered finite difference method with delayed detached-eddy simulation is employed to investigate the aerodynamic and aeroacoustic properties of the modified 30P30N multi-element high-lift airfoil. The experimental data from JAXA and FSU are used for quantitative comparisons. The calculated results agree reasonably well with the measured data in terms of the averaged quantities and fluctuating statistics. The physical mechanism relating to the unsteadiness, turbulent structures, narrow-band peaks associated with acoustic feedback loop *etc*. are all discussed. PSD analysis of additional numerical probes is implemented to in

depth investigate the types of noise sources. To sum up, the slat cove and main cove both function as shallow cavities. In terms of low-to-moderate frequencies, the slat cove shows noticeable narrow-band peaks whist main cove yields more broadband contents. Besides, the slat trailing-edge, main trailing-edge and flap trailing-edge all yield high frequency tones due to regular vortex shedding, corresponding to 21kHz, 40kHz and 20kHz, respectively. In addition, large massive separation occurs on the suction side of the flap, which results in the disappearance of the tones but yields the broadband contents. The acoustic field also demonstrates the slat component is a major noise contributor.

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# **Appendix**

## A. Power Spectral Density (PSD)

For a discrete sound signals  $p_n$ ,  $1 \le n \le N$ , the PSD is given by

$$S_{pp}(\omega) = 2\frac{N}{f_s} \left| \frac{1}{N} \sum_{n=1}^{N} p_n \exp(-i\omega n\delta t) \right|^2.$$

The sound power level (SPL) is evaluated by

$$SPL(\omega) = 10 \log_{10}(\frac{S_{pp}(\omega)}{P_{pof}^2}),$$

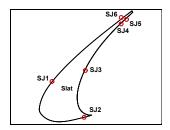
where  $P_{ref} = 2 \times 10^{-5} Pa$ . In this paper, we adopt window function before implementing the Fast Fourier Transform and average the sub-segments of the data to eliminate the spectral disparity.

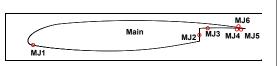
## B. Additional transducers for the pressure and velocity fluctuations

The coordinate of seven lines, the static pressure sensors on the surfaces and dynamic velocity pressure sensors are given below. The coordinates are normalized by 1m.

Tab. 3 Coordinate of seven cutting lines in Fig. 12, Fig. 14 and Fig. 16 along the slat shear layer trajectory.

|    | Starting point          | Ending point            |
|----|-------------------------|-------------------------|
| L1 | (-0.0097843, -0.042645) | (-0.0040602, -0.051872) |
| L2 | (-0.0059370, -0.038544) | (-0.0022806, -0.047464) |
| L3 | (-0.0025856, -0.033866) | (0.0078171, -0.041392)  |
| L4 | (-0.0018751, -0.027887) | (0.012723, -0.033202)   |
| L5 | (0.0006317, -0.024066)  | (0.014144, -0.024608)   |
| L6 | (0.0005379, -0.020406)  | (0.013099, -0.019539)   |
| L7 | (-0.0011512, -0.015458) | (0.013367, -0.014458)   |





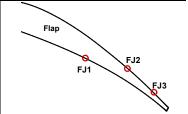
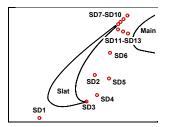
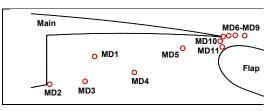


Fig. 36 Static surface pressure probes.

Tab. 4 Coordinate of static surface pressure probes.

|     | Slat      |     | Main     |     | Flap     |
|-----|-----------|-----|----------|-----|----------|
| SJ1 | -0.032100 | MJ1 | 0.029518 | FJ1 | 0.457959 |
| SJ2 | -0.015900 | MJ2 | 0.320044 | FJ2 | 0.488069 |
| SJ3 | -0.015343 | MJ3 | 0.334597 | FJ3 | 0.506743 |
| SJ4 | 0.002653  | MJ4 | 0.385814 |     |          |
| SJ5 | 0.005268  | MJ5 | 0.392126 |     |          |
| SJ6 | 0.002962  | MJ6 | 0.388792 |     |          |





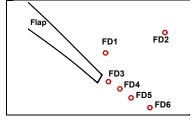


Fig. 37 Dynamic velocity probes.

Tab. 5 Coordinate of dynamic velocity probes.

|      | Slat                   |      | Main                  |     | Flap                  |
|------|------------------------|------|-----------------------|-----|-----------------------|
| SD1  | (-0.044614, -0.060982) | MD1  | (0.341888, 0.005040)  | FD1 | (0.517848, -0.057314) |
| SD2  | (-0.006206, -0.031227) | MD2  | (0.321419, -0.007660) | FD2 | (0.542104, -0.051880) |
| SD3  | (-0.011921, -0.049611) | MD3  | (0.337548, -0.006344) | FD3 | (0.517330, -0.066519) |
| SD4  | (-0.004663, -0.045135) | MD4  | (0.360006, -0.002272) | FD4 | (0.520882, -0.068416) |
| SD5  | (0.003615, -0.033636)  | MD5  | (0.382061, 0.008750)  | FD5 | (0.525307, -0.071020) |
| SD6  | (0.004347, -0.015865)  | MD6  | (0.400517, 0.014129)  | FD6 | (0.531690, -0.073986) |
| SD7  | (0.009984, 0.003998)   | MD7  | (0.403050, 0.014466)  |     |                       |
| SD8  | (0.011624, 0.005513)   | MD8  | (0.406037, 0.014669)  |     |                       |
| SD9  | (0.013701, 0.007480)   | MD9  | (0.410366, 0.014504)  |     |                       |
| SD10 | (0.016395, 0.009970)   | MD10 | (0.399148, 0.011960)  |     |                       |
| SD11 | (0.009870, 0.000331)   | MD11 | (0.400082, 0.009380)  |     |                       |
| SD12 | (0.013362, -0.001104)  |      |                       |     |                       |
| SD13 | (0.016811, -0.002479)  |      |                       |     |                       |

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